

## APPARATUS FOR TESTING INFRARED CAMERA

### BACKGROUND OF THE INVENTION

#### Field of the Invention

[001] 5           The present invention relates to an apparatus for testing infrared cameras, which are installed on a vehicle, for measuring distances to objects.

[002]           Priority is claimed on Japanese Patent Application No. 2002-290234, filed October 2, 2002, the content of which is incorporated herein by reference.

#### 10   Description of Related Art

[003]           A three-dimensional measuring method has been known in the art in which a distance to an object is determined using parallax between a pair of object images taken by a pair of cameras (stereo cameras). In such a method, an apparatus for correcting images must be used in order to accurately measure a distance to an object by correcting  
15   shift of images due to distortions of lenses and variations in focal lengths thereof. In an example of such an apparatus, a specific image pattern, such as a regular grid pattern, for measuring an amount of correction is simultaneously taken in advance using both stereo cameras, and the amounts of corrections in the coordinates are calculated pixel by pixel with regard to each image taken by each of the cameras. The calculated results are  
20   stored as a correction table for the coordinates, and the data stored in an image memory are corrected pixel by pixel using the correction table for the coordinates so that accurate image data are obtained. In a method disclosed in, for example, Japanese Unexamined Patent Application, First Publication No. Hei 11-325889, the corrections in shifting of  
25   images due to distortions of lenses and variations in focal lengths thereof are executed only in the vertical direction.

[004]

As an example to which the above-mentioned three-dimensional measuring method using stereo cameras is applied, a system is known which detects obstacles in front of a vehicle earlier than the driver of the vehicle does, and which notifies the driver of the existence of the obstacles. In this case, in general, infrared cameras, which enable taking infrared images, are used as the stereo cameras, in order to aid driving under poor visibility conditions.

[005]

As mentioned above, in order to correct shifting of images due to distortions of lenses and variations in focal lengths thereof, a specific image pattern, such as a regular grid pattern, for measuring an amount of correction is simultaneously taken in advance using both stereo cameras, and the amounts of corrections in the coordinates are calculated pixel by pixel with regard to each image taken by each of the cameras; however, in the case of infrared cameras used for the stereo cameras, a problem is encountered in that it is difficult to form a regular grid pattern which can be accurately taken by the infrared cameras.

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## SUMMARY OF THE INVENTION

[006]

In view of the above circumstances, an object of the present invention is to provide an apparatus for testing infrared cameras, which enables an easy measurement of errors in projected coordinates of objects in both the horizontal direction and vertical direction.

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[007]

In order to achieve the above object, the present invention provides an apparatus for testing infrared cameras including: a cover plate which has holes arranged in line, and which is adapted to emit an amount of infrared light; and an emission source which is disposed in parallel to and behind the cover plate as viewed from infrared cameras to be tested, and which is adapted to emit a different amount of infrared light when compared

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with the cover plate.

[008]

According to the apparatus for testing infrared cameras configured as described above, by disposing the emission source in parallel to and behind the cover plate which has holes arranged in line, and by making the emission source emit infrared light having an intensity which is greater than that of the infrared light emitted from the cover plate, infrared light emitting portions aligned in line can be formed using the infrared light passing through the holes formed in the cover plate. On the other hand, by making the emission source emit infrared light having an intensity which is less than that of the infrared light emitted from the cover plate, infrared light non-emitting portions aligned in line can be formed due to differences between the intensity of the infrared light emitted from the emission source and the intensity of the infrared light emitted from a portion of the cover plate other than the holes.

[009]

In the apparatus for testing infrared cameras, the emission source may include a metal plate, and a heat source which is connected to the metal plate.

[010] 15

According to the apparatus for testing infrared cameras configured as described above, infrared light can be uniformly emitted from the metal plate by heating the metal plate using the heat source, or by cooling the metal plate using the heat source. By making the uniformly emitted infrared light pass through the holes formed in the cover plate, the infrared light emitting portions which are accurately aligned or the infrared light non-emitting portions which are accurately aligned can be easily formed due to difference between the intensity of the infrared light emitted from the emission source and the intensity of the infrared light emitted from the cover plate.

[011]

In the apparatus for testing infrared cameras, the emission source may comprises a metal plate, and an element which is adhered to the metal plate, and which has an infrared emissivity that is higher than that of the cover plate.

[012] According to the apparatus for testing infrared cameras configured as described above, because the element having an infrared emissivity that is higher than that of the cover plate is adhered to the metal plate, the infrared light emitting portions which are accurately aligned can be formed at low cost by making the element uniformly emit  
5 infrared light, and by making the infrared light pass through the holes formed in the cover plate.

[013] In the apparatus for testing infrared cameras, the cover plate may have been subjected to a processing for reducing infrared light reflection.

[014] According to the apparatus for testing infrared cameras configured as described  
10 above, because the cover plate has been subjected to a processing for reducing infrared light reflection, the infrared light emitted from the emission source can be prevented from being reflected by a vehicle on which the infrared cameras to be tested are installed, and also, reflected infrared light can be prevented from being reflected by the cover plate.

[015] In the apparatus for testing infrared cameras, the cover plate may be vertically  
15 movable in front of the emission source as viewed from the infrared cameras to be tested from a first position at which testing of the infrared cameras is executed to a second position which is higher than the first position. The second position may be preferably set to be sufficiently higher than the first position so that the cover plate is not heated by a heat source of the emission source.

[016] 20 According to the apparatus for testing infrared cameras configured as described above, the vertical level of the cover plate can be adjusted in accordance with the vertical levels of the infrared cameras to be tested even when the vertical levels of the infrared cameras are changed. In addition, by moving the cover plate from a position in front of the emission source so as to make the distance between the cover plate and the emission  
25 source greater, the cover plate is prevented from being heated unnecessarily, which leads

to emission of unnecessary infrared light, or the cover plate is prevented from being cooled unnecessarily, which leads to non-emission of necessary infrared light.

#### BRIEF DESCRIPTION OF THE DRAWINGS

[017] 5 FIG. 1 is a perspective view showing an embodiment of an apparatus for testing infrared cameras according to the present invention.

[018] FIG. 2 is a plan view showing a target portion of the apparatus for testing infrared cameras according to the above embodiment.

[019] FIG. 3 is a front view showing the target portion of the apparatus for testing  
10 infrared cameras according to the above embodiment.

[020] FIG. 4 is a diagram showing a grayscale image of the target portion of the apparatus for testing infrared cameras according to the above embodiment taken by infrared cameras installed on a vehicle.

[021] FIG. 5 is a diagram showing a binarized image obtained by applying a  
15 binarization process to the grayscale image of the target portion.

[022] FIG. 6 is a flowchart showing a process for testing infrared cameras, in which the apparatus for testing infrared cameras according to the above embodiment and an image processing unit installed in the vehicle are used.

[023] FIG. 7 is a diagram showing a property curve of error in coordinates projected  
20 onto an image plane, which was obtained using the apparatus for testing infrared cameras according to the above embodiment.

[024] FIG. 8A is a schematic diagram illustrating the relationship between a distance R from the center of a lens to an object and the coordinates of the geometric center of the object, and FIG. 8B is a diagram showing the property curve of error in coordinates  
25 projected onto an image plane, which was obtained using the apparatus for testing

infrared cameras according to the above embodiment, as a property curve of error in coordinates with respect to the distance R.

[025] FIG. 9 is a schematic diagram illustrating mounting angle (panning angle  $\theta$ ) of an infrared camera installed on a vehicle.

[026] 5 FIG. 10 is a diagram showing a grayscale image of the target portion of the apparatus for testing infrared cameras according to the above embodiment taken by the infrared cameras installed on the vehicle.

[027] FIG. 11 is a diagram showing another property curve of error in coordinates projected onto an image plane, which was obtained using the apparatus for testing  
10 infrared cameras according to the above embodiment in an alternative process.

#### DETAILED DESCRIPTION OF THE INVENTION

[028] An embodiment of the present invention will be explained below with reference to appended drawings.

[029] 15 FIG. 1 is a perspective view showing an embodiment of an apparatus for testing infrared cameras according to the present invention, which is to be installed in a manufacturing line in a plant. FIG. 2 is a plan view showing a target portion of the apparatus for testing infrared cameras according to the present embodiment. FIG. 3 is a front view showing the target portion of the apparatus for testing infrared cameras.

[030] 20 As shown in FIG. 1, the apparatus for testing infrared cameras according to the present embodiment includes a back plate 2 and a front plate 3 which together form a target portion that is disposed in front of a vehicle 1 which is provided with infrared cameras to be tested at the front end thereof. The back plate 2 of an aluminum plate is acts as an infrared light emission source when the entirety thereof is heated or cooled.

25 The front plate 3 of an aluminum plate is disposed closer to the vehicle 1 than from the

back plate 2. Circular holes (hereinafter referred to as target holes) having the same size with respect to each other are formed in the front plate 3 at a regular interval.

[031]

The back plate 2 is a plate-shaped element whose width in the horizontal direction is approximately the same as that of the vehicle 1, and whose height in the vertical direction is sufficiently large when compared with the vehicle 1 regardless of models of the vehicle 1 so that testing of the infrared cameras is allowed wherever the infrared cameras are installed on the vehicle 1. The back plate 2 is disposed at lower portions of pillars 4a and 4b. On the other hand, the front plate 3 is made vertically movable in front of the back plate 2 and along the pillars 4a and 4b. By being controlled by the controller 5, the front plate 3 is movable from the ground height to a level corresponding to approximately two times the height of the back plate 2. Accordingly, the vertical level of the target portion including the back plate 2 and the front plate 3 can be adjusted to a level of the infrared cameras even when the level of the infrared cameras are changed depending on the models of the vehicle 1.

[032] 15

The back plate 2 and the front plate 3 will be further explained below in detail. As shown in FIG. 2, the back plate 2 is provided with temperature adjusting devices 6 such as heaters or Peltier elements on the backside thereof as viewed from the vehicle 1 in order to execute heating or cooling of the entirety of the back plate 2.

[033]

The direct transmission of heat from the back plate 2 to the front plate 3 is prevented by supporting the front plate 3 by the pillars 4a and 4b so that the front plate 3 is separated from the back plate 2 by an appropriate distance, and by fabricating the pillars 4a and 4b with a material having low thermal conductivity. When the front plate 3 is moved to the uppermost portions of the pillars 4a and 4b, the front plate 3 is not affected by heating and cooling of the back plate 2.

[034] 25

As shown in FIG. 3, the front plate 3 has the circular target holes (eleven target

holes H1 to H11 in this embodiment) which are arranged in line in the horizontal direction along the center line of the front plate 3 at a regular interval; therefore, the back plate 2 can be seen from the vehicle 1 through the target holes H1 to H11. In addition, raised paper 3a having low reflectance is adhered to the front face (front surface) of the front plate 3 as viewed from the vehicle so that the infrared light reflected by the vehicle 1 or emitted from the vehicle 1 will not be reflected by the front plate 3 and will not return to the vehicle 1.

[035] In the target portion as configured above, the back plate 2 and the front plate 3 are overlaid each other, and the back plate 2 is heated. The infrared light emitted from the back plate 2 is taken by the infrared cameras installed on the vehicle 1 through the target holes H1 to H11 formed in the front plate 3 to obtain a grayscale image shown in FIG. 4. A binarization process is applied to the grayscale image shown in FIG. 4 to obtain a binarized image shown in FIG. 5.

[036] In contrast, when the back plate 2 is cooled, the infrared light emitted from the front plate is take by the infrared cameras; therefore, another binarized image is obtained which is reversed in white and black when compared with the binarized image shown in FIG. 4.

[037] In a state in which the back plate 2 is heated to make the back plate 2 emit infrared light, infrared light having higher intensity can be obtained by adhering a material having an infrared reflectance greater than 0.9 such as paper or carbon to the back plate 2. Accordingly, when infrared light having higher intensity is desired, the back plate 2 is heated using the temperature adjusting devices 6 in addition to adhering paper or carbon to the back plate 2. When low cost is desired for the apparatus for testing infrared cameras, the temperature adjusting devices 6 may be omitted, and just the back plate 2 having paper or carbon thereon may be used as the infrared light emission



source.

[038]               Next, a verification process for the on-vehicle infrared cameras using the apparatus for testing infrared cameras of the present embodiment will be explained below.

[039]     5               FIG. 6 is a flowchart showing the verification process for the infrared cameras, in which the apparatus for testing infrared cameras according to the above embodiment and an image processing unit installed in the vehicle 1 are used.

[040]               In FIG. 6, the image processing unit obtains infrared images as an output signal of the stereo infrared cameras (step S1), executes an A/D conversion (step S2), and stores  
10       grayscale images in an image memory (step S3). A right image of the target holes H1 to H11 is obtained by a right infrared camera, and a left image of the target holes H1 to H11 is obtained by a left infrared camera.

[041]               In step S3, the grayscale images such as shown in FIG. 4 is obtained, and then a binarization process is applied to each of the right and left images to obtain the binarized  
15       images such as shown in FIG. 5 (step S4). In the binarization process, regions in the image that are brighter than a brightness threshold ITH are deemed as "1" (i.e., white), and regions in the image that are darker than the brightness threshold ITH are deemed as "0" (i.e., black).

[042]               Next, the geometric center of each of the target holes H1 to H11 in the binarized  
20       image is calculated (step S5).

[043]               Next, an error in projected coordinates are calculated (step S6) based on the differences between the theoretical projected X coordinates and the observed X coordinates of the geometric centers obtained in step S5. More specifically, the coordinates of the target holes H1 to H11 in actual space projected onto the image (the  
25       theoretical projected X coordinates) are obtained using Equation (1) shown below. The

errors in projected X coordinates are obtained by subtracting the observed X coordinates of the geometric centers from the theoretical projected X coordinates.

$$x=(F \cdot X)/(p \cdot Z) \dots \text{Equation (1)}$$

[044] In Equation (1), “x” indicates the coordinate of the target hole projected onto the  
5 image, “X” indicates position of the target hole in the actual space shown in FIG. 4, “Z” indicates the distance between the target hole in the actual space and the camera, “p” indicates pitch of pixels, and “F” indicates the focal length of the lens of the camera.

[045] Moreover, with regard to each position of the binarized target holes H1 to H11 shown in FIG. 5, an error in projected X coordinate is calculated, and then a property  
10 curve of error in coordinates projected onto the image plane for the errors in projected X coordinates of the target holes H1 to H11 is obtained with regard to each of the right and left images (step S7). More specifically, as shown in FIG. 7, the property curve of error in the coordinates projected onto the image plane, which corresponds to the errors in projected X coordinates of the target holes H1 to H11, is drawn by plotting points in such  
15 a manner that the observed X coordinates of the geometric centers are measured along the x-axis, and the errors in projected X coordinates are measured along the y-axis, and by curve-fitting the plotted points using a line or using a polynomial approximation. Equation (2) shown below is applied to a six-degree polynomial approximation for the property curve of error in the coordinates projected onto the image plane as shown in FIG.  
20 7. The “α” shown in FIG. 7, for example, indicates the error in the projected coordinate of the target hole H9.

$$y=a \cdot x^6+b \cdot x^5+c \cdot x^4+d \cdot x^3+e \cdot x^2+f \cdot x+g \dots \text{Equation (2)}$$

The obtained property curve of error in the coordinates projected onto the image plane is stored as a camera coordinates correction parameter (step S8).

[046] 25 The property curve of error in the coordinates projected onto the image plane

shown in FIG. 7 indicates the errors in the projected X coordinate with respect to the observed X coordinates of the geometric centers of the objects (target holes); however, another property curve of error in the coordinates projected onto the image plane, which indicates the errors in the projected coordinate with respect to the distance from the center of the lens of the camera, may be drawn and used because distortion in a lens is, in general, symmetrical about the center of the lens. More specifically, when the observed coordinates of the geometric center of an object is expressed by “(Xp, Yp)” as shown in FIG. 8A, and the distances R from the center of the lens calculated using Equation (3) are measured along the x-axis instead of the observed X coordinates of the geometric centers in the case of FIG. 7, the errors in the projected coordinate with respect to the distances R from the center of the lens are indicated as shown in FIG. 8B.

$$R=(Xp^2+Yp^2)^{1/2} \dots \text{Equation (3)}$$

[047] In the above method for obtaining the property curve of error in the coordinates projected onto the image plane based on the differences between the theoretical projected X coordinates and the observed X coordinates of the geometric centers, the position and angle of the camera must be adjusted so that the center target hole H6, which is to be the basis of measurement, is positioned at the center of the image in order to use Equation (1); however, it is difficult to accurately adjust the position and angle of the camera due to limitations in accuracy of installation of the cameras at a factory, due to limitations in accuracy of equipment in the factory.

[048] However, even when the position and angle of the camera are not adjusted, the theoretical projected coordinates can be calculated if an installation angle (i.e., a panning angle)  $\theta$  of the camera, which is illustrated in FIG. 9, can be found. In this case, the coordinates projected onto the image plane (i.e., the theoretical projected X coordinates) of the target holes H1 to H11 are calculated based on the positions of the target holes H1

to H11 in the actual space using Equation (4).

$$X = \{F \cdot (X \cdot \cos \theta + Z \cdot \sin \theta)\} / \{p \cdot (-X \cdot \sin \theta + Z \cdot \cos \theta)\} \dots \text{Equation (4)}$$

[049] In Equation (4), “x” indicates the coordinate of the target hole projected onto the image, “X” indicates position of the target hole in the actual space shown in FIG. 4, “Z”  
5 indicates the distance between the target hole in the actual space and the camera, “p” indicates pitch of pixels, “F” indicates the focal length of the lens of the camera, and “θ” indicates the panning angle of the camera.

[050] Next, another method for obtaining the property curve of error in the coordinates projected onto the image plane using the apparatus for testing infrared cameras according  
10 to the present embodiment will be explained.

[051] In another method for obtaining the property curve of error in the coordinates projected onto the image plane, the property curve of error in the coordinates projected onto the image plane is obtained based on the differences between the observed distances and the theoretical distances from the center target hole H6, as the basis of measurement,  
15 to the other target holes.

[052] More specifically, in step S3 shown in FIG. 6, grayscale images are obtained, and then a binarization process is applied to each of the right and left images to obtain the binarized images. In the binarization process, regions in the image that are brighter than a brightness threshold ITH are deemed as “1” (i.e., white), and regions in the image  
20 that are darker than the brightness threshold ITH are deemed as “0” (i.e., black).

[053] Next, the geometric center of each of the target holes H1 to H11 in the binarized image is calculated.

[054] As shown in FIG. 10, the distances on the image from the center target hole H6 to the other target holes (i.e., theoretical distances LR1 to LR11) are calculated using  
25 Equation (5). Next, the errors in projected X coordinates (the errors in projected X

coordinates = the observed distances from the center target hole H6 to the other target holes – the theoretical distances from the center target hole H6 to the other target holes) are obtained based on the observed distances from the center target hole H6 to the other target holes (LJ1 to LJ11) and the theoretical distances from the center target hole H6 to the other target holes (LR1 to LR11).

$$l = (F \cdot L) / (p \cdot Z) \dots \text{Equation (5)}$$

[055] In Equation (5), “l” indicates the distances on the image from the center target hole H6 to the other target holes, “L” indicates the distances in the actual space from the center target hole H6 to the other target holes as shown in FIG. 10, “Z” indicates the distances in the actual space from the target holes to the camera, “p” indicates pitch of pixels, and “F” indicates the focal length of the lens of the camera.

[056] Moreover, with regard to each position of the binarized target holes H1 to H11 shown in FIG. 5, the error in the projected X coordinate is calculated as shown in TABLE 1, and then a property curve of error in the coordinates projected onto the image plane is obtained based on the errors in the projected X coordinates of the target holes H1 to H11. More specifically, as shown in FIG. 11, the property curve of error in the coordinates projected onto the image plane, which corresponds to the errors in projected X coordinates of the target holes H1 to H11, is drawn by plotting points in such a manner that the observed X coordinates of the geometric centers (i.e., the observed distances from the target hole H6 and to the other target holes) are measured along the x-axis, and the errors in projected X coordinates are measured along the y-axis, and by curve-fitting the plotted points using a line or using a polynomial approximation. Equation (2) shown below is applied to a six-degree polynomial approximation for the property curve of error in the coordinates projected onto the image plane as shown in FIG. 11. The “ $\beta$ ” shown in FIG. 11, for example, indicates the error in the projected X coordinate (i.e.,

(LJ9-LR9)) corresponding to the distance from the center target hole H6 to the target hole H9.

TABLE 1

Target hole	Observed distance from H6 to each of the other target holes	Theoretical distance from H6 to each of the other target holes	Error in the projected X coordinate
H1	LJ1	LR1	LJ1-LR1
H2	LJ2	LR2	LJ2-LR2
H3	LJ3	LR3	LJ3-LR3
H4	LJ4	LR4	LJ4-LR4
H5	LJ5	LR5	LJ5-LR5
H6	-	-	-
H7	LJ7	LR7	LJ7-LR7
H8	LJ8	LR8	LJ8-LR8
H9	LJ9	LR9	LJ9-LR9
H10	LJ10	LR10	LJ10-LR10
H11	LJ11	LR11	LJ11-LR11

[057] 5 In the method for obtaining the property curve of error in the coordinates projected onto the image plane based on the differences between the observed distances and the theoretical distances from the center target hole H6, as the basis of measurement, to the other target holes, even when there is a panning angle  $\theta$  of the cameras, the property curve of error in the coordinates projected onto the image plane can be

10 accurately obtained based on the differences between the observed distances and the theoretical distances from the center target hole H6 to the other target holes because the distances from the center target hole H6 to the other target holes will not change with the panning angle  $\theta$ .

[058] As explained above, the apparatus for testing infrared cameras according to the

15 present embodiment includes the front plate 3 having the holes arranged in line, and the

back plate 2, as the infrared light emission source, disposed behind the front plate 3 while being in parallel with the front plate 3. In the apparatus for testing infrared cameras, by heating the back plate 2 using the temperature adjusting device 6 so that the back plate 2 emits infrared light having an intensity which is greater than that of the infrared light emitted from the front plate 3, the infrared light emitting portions aligned in line can be formed using the infrared light passing through the holes formed in the front plate 3. In contrast, when the back plate 2 is cooled using the temperature adjusting device 6, because the front plate 3 emits infrared light having an intensity which is greater than that of the infrared light emitted from the back plate 2, white and black in the image taken by the infrared camera are reversed.

[059] Moreover, if the front plate 3 has been subjected to a processing for reducing infrared light reflection, the infrared light, which is emitted from the back plate 2, and is then reflected by the vehicle 1 on which the infrared cameras to be tested are installed, can be prevented from being reflected by the front plate 3, and thus effects of the reflected infrared light in the test of the infrared cameras can be eliminated.

[060] Furthermore, by adhering an element having a high infrared emissivity such as paper or carbon to the back plate 2 so that the element emits infrared light having an intensity which is greater than that of the infrared light emitted from the front plate 3, the cost of the apparatus for testing infrared cameras can be reduced because the temperature adjusting device 6 for heating the back plate 2 may be omitted.

[061] In addition, by making the front plate 3 vertically movable in front of the back plate 2, the vertical level of the front plate 3 can be adjusted in accordance with the vertical levels of the infrared cameras even when the vertical levels of the infrared cameras are changed due to change in the model of the vehicle 1. Moreover, by moving the front plate 3 from a position in front of the back plate 2 so as to make the distance

between the front plate 3 and the back plate 2, the front plate 3 is prevented from being heated unnecessarily, which leads to emission of unnecessary infrared light, or the front plate 3 is prevented from being cooled unnecessarily, which leads to non-emission of necessary infrared light.

[062] 5           Accordingly, the distortions of the lenses in various directions and variations in the focal lengths of the lenses used in the infrared cameras to be tested can be confirmed as the property curve of error in the coordinates projected onto the image plane by taking the images of the infrared emitting portions uniformly formed using the apparatus for testing infrared cameras, and by comparing the positions of the infrared emitting portions  
10 in the actual space with the coordinates of the infrared emitting portions projected onto the image plane.

#### Advantageous Effects of the Invention

[063]           As explained above, according to the apparatus for testing infrared cameras of  
15 the present invention, by disposing the emission source in parallel to and behind the cover plate which has holes arranged in line, and by making the emission source emit infrared light having an intensity which is greater than that of the infrared light emitted from the cover plate, infrared light emitting portions aligned in line can be formed using the infrared light passing through the holes formed in the cover plate. On the other  
20 hand, by making the emission source emit infrared light having an intensity which is less than that of the infrared light emitted from the cover plate, infrared light non-emitting portions aligned in line can be formed due to difference between the intensity of the infrared light emitted from the emission source and the intensity of the infrared light emitted from a portion of the cover plate other than the holes.

[064] 25           Therefore, the testing of the infrared cameras can be accurately performed using



the infrared light emitting portions which are clearly delimited, or using the infrared light non-emitting portions which are taken by the infrared cameras as a reversed pattern when compared with the infrared light emitting portions.

[065] According to another apparatus for testing infrared cameras of the present  
5 invention, the infrared light emitting portions which are accurately aligned or the infrared light non-emitting portions which are accurately aligned can be easily formed by heating the metal plate using the heat source, or by cooling the metal plate using the heat source so that infrared light is uniformly emitted from the metal plate.

[066] Therefore, by controlling the heat source, the contrast in the image of the  
10 emission source taken by the infrared cameras can be increased, and the testing of the infrared cameras can be accurately performed.

[067] According to another apparatus for testing infrared cameras of the present  
invention, because the element having an infrared emissivity that is higher than that of the cover plate is adhered to the metal plate, the infrared light emitting portions which are  
15 accurately aligned can be formed at low cost by making the element uniformly emit infrared light.

[068] Therefore, the cost of the apparatus for testing infrared cameras can be reduced.

[069] According to another apparatus for testing infrared cameras of the present  
invention, because the cover plate has been subjected to a processing for reducing  
20 infrared light reflection, the infrared light emitted from the emission source can be prevented from being reflected by a vehicle on which the infrared cameras to be tested are installed, and also reflected infrared light can be prevented from being reflected by the cover plate.

[070] Therefore, distortions in the infrared light emitting portions or in the infrared  
25 light non-emitting portions due to the infrared light reflected by the vehicle and reflected

by the cover plate can be prevented, and the testing of the infrared cameras can be accurately performed.

[071]

According to another apparatus for testing infrared cameras of the present invention, the vertical level of the cover plate can be adjusted in accordance with the vertical levels of the infrared cameras to be tested. In addition, by moving the cover plate from a position in front of the emission source, the cover plate is prevented from being heated unnecessarily, which leads to emission of unnecessary infrared light, or the cover plate is prevented from being cooled unnecessarily, which leads to non-emission of necessary infrared light.

[072] 10

Therefore, in a manufacturing line of automobiles, for example, the vertical level of the cover plate can be adjusted to the level of the infrared cameras to be tested depending on the models of the vehicle. The cover plate is disposed in front of the emission source only when the cover plate is required in the testing of the infrared cameras which is not continuously performed so that the infrared light emitting portions which are accurately aligned or the infrared light non-emitting portions which are accurately aligned are formed, and thus the testing of the infrared cameras can be accurately performed at any time.

[073]

While preferred embodiments of the invention have been described and illustrated above, it should be understood that these are exemplary of the invention and are not to be considered as limiting. Additions, omissions, substitutions, and other modifications can be made without departing from the spirit or scope of the present invention. Accordingly, the invention is not to be considered as being limited by the foregoing description, and is only limited by the scope of the appended claims.